



The Seascope Underwater Inclinator, depth rated to 1000 m, with variable outputs and measuring ranges.

The UWIM-series of inclination sensors measures angles in 1 or 2 axes. These products are based on robust MEMS technology, in which capacitance differences can be converted into an analogue voltage within a micro-mechanical sensor chip. This analogue voltage is proportional to the angle to which the sensor is exposed. The modular design makes it easy to adapt the sensors to specific requirements.

An inclination sensor is used in situations where accurate positioning or constant monitoring of the angle in relation to gravitational pull is essential. An inclination sensor measures the angle with respect to a horizontal position, whereby an imaginary line from the center of the earth serves as a reference. An inclination sensor has a very wide range of applications since it can be mounted anywhere and offers flexibility in mechanical design. The sensor output has two components: a static (slope) component and a dynamic (acceleration) component. The sensor output is always a combination of these two components. The inclination sensors from DIS have a standard bandwidth of 10 Hz, although it is possible to reduce this bandwidth further at the client's request.

Features

- 1 or 2 axes
- Based on MEMS-tech.
- Bandwidth 10 Hz
- Depth rated up to 1000 m

Applications

- Tilt protection
- Roll & pitch measurement
- Platform levelling
- Angle monitoring

Applications

Inclination sensors are used for various applications such as: tilt protection, roll and pitch measurements and angle monitoring at ROV's, Stingers and Dredging equipment.

Specifications

Single axis measurement range	: $\pm 10^\circ$; $\pm 30^\circ$; $\pm 90^\circ$; 0 – 360°
Double axis measurement range	: $\pm 10^\circ$; $\pm 30^\circ$; $\pm 90^\circ$
Energy supply	: 5V DC or 10-30V DC
Analogue output	: 0,5-4,5V or 4-20 mA, 0 – 10 Volt
Digital output	: CANopen, Serial RS232/RS485
Accuracy	: depending on model and range: up to 0.02°

Distributed by:

Family Overview

Measuring range
Max. # of axis
Switching output
Centering function
Redundant
Output format
Output bandwidth
Output function

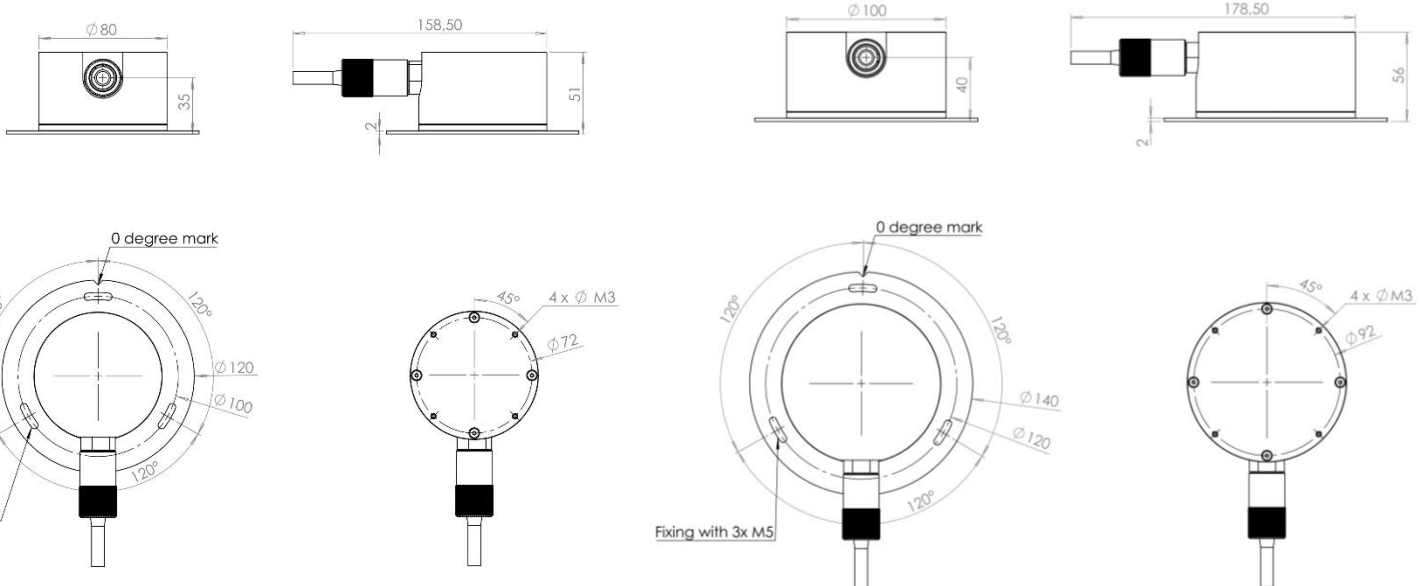
UWIM-B			UWIM-A				UWIM-A CANopen			UWIM-AX	
±10°	±30°	±90°	±10°	±30°	±90°	±15°	30..360°	±30°	±90°	360°	360°
2			2				1			1	
no			2x NPN / 2x PNP 100mA				no			no	
no			yes				Yes (CAN object dictionary)			Yes (CAN object dictionary)	
no			no				no			no	
4-20mA / 0.5-4.5V			4-20mA / 0.5-4.5V				CANopen			CANopen	
0 - 10 Hz			0 - 10 Hz				0 - 10 Hz			0 - 10 Hz	
Output = x + y*(sin(α))			Output = x + y*(α)				Output = x + y*(α)			Output = x + y*(α)	

Resolution
Accuracy (typ.)
Temp. Coefficient (typ.)

0,03°			0,01°		0,004°	0,01°	0,01°			0,001°	
0,3°	0,6°	0,9° (-45° ..+45°)	0,04°	0,04°	0,08° (-45° ..+45°)	0,02°	0,07°	0,04°	0,06° (-45° ..+45°)	0,06°	0,04° over full Temp. Range (Active Temp. Comp.)
offset error excluded, 1° typ.											
0,01° /K			0,005° /K				0,005° /K			0 (-20° to +60° C)	

Size
Material Housing
Operating Depth
Weight in air
Weight in water
Temp. Range
Connection standard

Ø80x51 mm		Ø80x51 mm		Ø100x56 mm		Ø100x56 mm	
POM	SS316	POM	SS316	POM	SS316	POM	SS316
200 msw	1000 msw	200 msw	1000 msw	200 msw	1000 msw	200 msw	1000 msw
510 gr.	1600 gr.	510 gr.	1600 gr.	700 gr.	2400 gr.	700 gr.	2400 gr.
400 gr.	1270 gr.	400 gr.	1270 gr.	550 gr.	1900 gr.	550 gr.	1900 gr.
-25 .. +85°C		-40 .. +85°C		-40 .. +85°C		-40 .. +85°C	
MCBH5MSS		MCBH8MSS		MCBH5MSS		MCBH8MSS	



Number of axis
 1 = 1 axis
 2 = 2 axis

Material
 S = AISI316
 P = POMC

Degrees
 45 = 45° degree
 90 = 90° degree
 180 = 180° degree
 360 = 360° degree

Analog output
 AI = 4-20 mA
 AV = 0,5 - 4,5 Volt
 AV1 = 0 - 10 Volt
 CAN = Can open
 232 = Serial rs232
 485 = Serial rs485

Connector
 C5 = MCBH5MSS
 C8 = MCBH8MSS

Accuracy
 S = Standard
 H = High
 X = Extra high

Position
 H = Horizontal
 V = Vertical
 HV = Horizontal & Vertical
 N/A = Not applicable

UWIM P A 1 - V 360 S - AI C5

UnderWater InclinoMeter

Housing
 A = ø 100 mm
 B = ø 80 mm